



Fakultät für Informatik  
Lehrstuhl für Echtzeitsysteme und Robotik

# Titel der Arbeit

**Vorname und Name**

Seminar *Kognitive Robotik* (SS13)

**Betreuer:** Name des Betreuers

**Leitung:** Prof. Alois Knoll

**Abgabetermin:** 11. August 2013

# Bare Demo of IEEEtran.cls for Conferences

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**Abstract**—The abstract goes here.

## I. INTRODUCTION

This demo file is intended to serve as a “starter file” for IEEE conference papers produced under L<sup>A</sup>T<sub>E</sub>X using IEEEtran.cls version 1.8 and later. I wish you the best of success.

mds

December 27, 2012

### A. Subsection Heading Here

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1) Subsubsection Heading Here: Subsubsection text here.

## II. CONCLUSION

The conclusion goes here.

## REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to L<sup>A</sup>T<sub>E</sub>X*, 3rd ed. Harlow, England: Addison-Wesley, 1999.

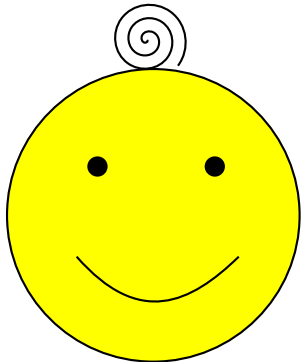


Fig. 1. A vector graphic loaded from a PDF file



Fig. 2. A bitmap graphic loaded from a PNG file